



NEMO110 Unmanned Surface Vessel

NEMO110 is an unmanned vessel system with integrated single-beam echosounder. Thanks to this versatile solution it is possible to carry out surveys and measurements in areas not reachable, or difficult to reach, by crewed ships such as shallow waters and coastal areas. NEMO110 can be used in underwater topographic surveying and mapping, hydrological surveying and underwater hidden pipe detection.

### Super Power System

The hull propulsion system has strong power, high reliability, stable driving and it is suitable for various water flow environment measurement. The vessel can reach 5m/s speed.

### **Smooth Sailing Performance**

The vessel has a good seal at sea and in waterways thanks to its design.

### Easy to Maintain

Modular design makes it convenient for quick installation and disassembly. **Anticollision Sensor** 

Avoid every obstacle. The anticollission sensor installed on the front of the vessel can detect an obstacle and stop the propellers.





### **GPS NAVIGATION**

Thanks to a Stonex GNSS receiver, Nemo110 has an excellent on board real time navigation solution with high accuracy.



5 M/S SPEED

Brushless DC motor. Maximum Speed 5 m/s.



### HIGH BATTERY CAPACITY

Long battery life 6 hours of continuous use.



### SMALL AND LIGHTWEIGHT

Lightweight. Just 20 kg with battery and echosounder. Dimensions: 1180 × 630 × 340 mm.



### RUGGED

With IP67 Certification and Kevlar + carbon fiber material hull.









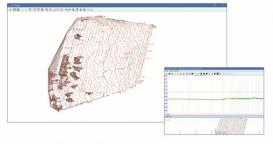
## Software

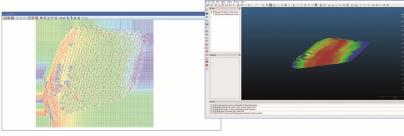
The joint use of Navigation software and Bathymetry software provide the operator a full working procedure.

With Navigation software the operator could plan missions, trajectories and waypoints directly on the map both in manual and automatic way. The aquatic drone can complete the mission autonomously.

With Bathymetry software the operator checks the data collected by echosounder; at the end of the mission, he can elaborate them, improving the quality of the survey.







# **Applications**

- Underwater topographic surveying and mapping
- Monitoring of small canals
- Monitoring of inaccessible areas
- Underwater pipes detection
- Surveying in shallow waters





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# NEMO110 TECHNICAL FEATURES

HULL	
Size (w*h*d)	1180mm*630mm*340mm
Material	Kevlar + carbon fiber composite material
Weight	15kg
Standard displacement	25kg
Maximum displacement	30kg
Wind and wave	Wind: 5 level
resistance rating	Wave: sea state 3 level
Boat Type	М Туре
Anti-settling design	Closed-cell foam filling and fully enclosed
	bulkhead anti-sink design
Camera	360° Panoramic camera
Navigation light	Two-color navigation lights
POWER	
Battery life	6 hours at economy speed (1.5-2m/s)
Economy speed	1.5-2m/s
Max. speed	≥5m/s
Propeller motor type	Brushless DC motor
Propeller	Bypass propeller

NAVIGA.	TION AND	CONTROL
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Navigation Mode	Manual mode/automatic mode/cruise control
Guided system	GPS/Beidou, RTK, or specified GNSS devices
Direction control	Differential steering
Lost protection	Automatic return when lost or low battery

1. Available on request

COMMUNICATION

Sensor

	Dual communication (wireless point-
Communication mode	to-point communication/network
	communication)
Communication distance	Bridge 3km/network communication
Communication distance	long range
Hardware configuration	Support mainstream laptop/tablet
mardware configuration	Dedicated ground station (optional)
Base station operating system	Windows10 and better
Base station software	Support unmanned ship management,
	line management, status display, data
	management, log functions
Handheld remote control	(IP67) Waterproof and dustproof,
unit	digital HD map transmission, ultra-long
	link, ultra-long endurance
CARRYING DEVICE	
	Single-beam echosounder

Side-scan sonar <sup>1</sup>

ADCP<sup>1</sup>

Illustrations, descriptions and technical specifications are not binding and may change

